Lecture 1 Interacting particle systems and the backward process

Jan M. Swart

Rouen

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- Poisson construction of finite state space Markov processes
- Countable state spaces
- Interacting particle systems
- The backward process

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Let **S** be a finite set.

A probability kernel on **S** is a function $K : \mathbf{S} \times \mathbf{S} \rightarrow [0, 1]$ such that

$$\sum_{y\in S} \mathcal{K}(x,y) = 1$$
 $(x\in S).$

We can multiply probability kernels as matrices:

$$(\mathcal{K}\mathcal{L})(x,z) := \sum_{y \in \mathbf{S}} \mathcal{K}(x,y)\mathcal{L}(y,z) \qquad (x,z \in \mathbf{S}).$$

We can also view kernels as linear operators that act on functions $f: \mathbf{S} \to \mathbb{R}$ as

$$\mathcal{K}f(x) := \sum_{y \in \mathbf{S}} \mathcal{K}(x, y)f(y).$$

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Continuous-time Markov chains

Let **S** be a finite set. A *Markov semigroup* is a collection of probability kernels $(P_t)_{t\geq 0}$ on **S** such that

$$\lim_{t\downarrow 0} P_t = P_0 = 1 \quad \text{and} \quad P_s P_t = P_{s+t} \qquad (s,t\geq 0).$$

Each such Markov semigroup is of the form

$$P_t = e^{tG} := \sum_{n=0}^{\infty} \frac{1}{n!} (tG)^n,$$

where the generator G is a matrix of the form

$$G(x, y) \ge 0 \quad (x \ne y) \quad \text{and} \quad \sum_{y \in \mathbf{S}} G(x, y) = 0.$$

One has $P_t(x, y) = 1_{\{x=y\}} + tG(x, y) + O(t^2)$ as $t \rightarrow 0$.
We call $G(x, y)$ the *rate* of jumps from x to y $(x \ne y)$.

Random mapping representations

We view generators as linear operators that act on functions $f: \mathbf{S} \to \mathbb{R}$ as

$$Gf(x) := \sum_{y \in \mathbf{S}} G(x, y) f(y) \qquad (x \in \mathbf{S}).$$

Then $P_t f = f + tGf + O(t^2)$ as $t \to 0$. Each generator G can be written in the form

$$Gf(x) = \sum_{m \in \mathcal{G}} r_m \{f(m(x)) - f(x)\},\$$

where \mathcal{G} is a finite set whose elements are functions $m : \mathbf{S} \to \mathbf{S}$ and $(r_m)_{m \in \mathcal{G}}$ are nonnegative rates.

We call this a random mapping representation of G.

Random mapping representation are usually far from unique.

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Poisson construction of Markov processes

Each random mapping representation of G corresponds to a Poisson construction of the Markov process.

Let ρ be the measure on $\mathcal{G}\times\mathbb{R}$ defined by

$$hoig(\{m\}\times[s,t]ig):=r_m(t-s)\qquad(m\in\mathcal{G},\ s\leq t).$$

Let ω be a Poisson point set on $\mathcal{G} \times \mathbb{R}$ with intensity ρ and let

$$\omega_{s,u} := \{(m,t) \in \omega : s < t \le u\} \qquad (s \le u).$$

Define random maps $(X_{s,u})_{s \leq u}$ by

$$\begin{split} \mathbb{X}_{s,u} &:= m_n \circ \cdots \circ m_1 \\ \text{with} \quad \omega_{s,u} &:= \big\{ (m_1, t_1), \dots, (m_n, t_n) \big\} \\ \text{and} \quad t_1 < \cdots < t_n. \end{split}$$

The random maps $(\mathbb{X}_{s,u})_{s \leq u}$ form a *stochastic flow:*

$$\mathbb{X}_{s,s} = 1$$
 and $\mathbb{X}_{t,u} \circ \mathbb{X}_{s,t} = \mathbb{X}_{s,u}$ $(s \leq t \leq u).$

This stochastic flow has independent increments in the sense that

$$\mathbb{X}_{t_0,t_1},\ldots,\mathbb{X}_{t_{n-1},t_n}$$
 are independent $\forall t_0 < \cdots < t_n$.

Let X_0 be an **S**-valued random variable, independent of ω , and let $s \in \mathbb{R}$. Then

$$X_t := \mathbb{X}_{s,s+t}(X_0) \qquad (t \ge 0)$$

defines a Markov process $(X_t)_{t\geq 0}$ with generator G.

The contact process

Let Λ be a finite set and let $\lambda(j, i) \ge 0$ $(i, j \in \Lambda)$. Let $\mathbf{S} := \{0, 1\}^{\Lambda}$ be the set of all functions $x : \Lambda \to \{0, 1\}$. For $x \in \mathbf{S}$ and $\Delta \subset \Lambda$, we let

$$x_{\Delta} = (x(i))_{i \in \Delta}$$

denote the restriction of x to Δ .

For $x, y \in \mathbf{S}$ such that $x_{\Lambda \setminus \{i\}} = y_{\Lambda \setminus \{i\}}$ for some $i \in \Lambda$, let

$$G(x,y) := \begin{cases} \sum_{j \in \Lambda} x(j)\lambda(j,i) & \text{if } x(i) = 0, \ y(i) = 1, \\ 1 & \text{if } x(i) = 1, \ y(i) = 0, \end{cases}$$

and let G(x, y) := 0 if x and y differ in more than one site.

The Markov process with generator G is called the contact process with infection rates $(\lambda(i,j))_{i \neq j}$ and death rate 1. Often, the lattice Λ has the structure of a graph. Write $i \sim j$ if i and j are neighbours.

The nearest-neighbour contact process has infection rates

$$\lambda(j,i) = \lambda \mathbf{1}_{\{i \sim j\}}$$
 $(i,j \in \Lambda),$

where $\lambda \geq 0$ is the *infection rate*.

The random mapping representation

For each $i, j \in \Lambda$, we define a branching map $bra_{ji} : \{0, 1\}^{\Lambda} \to \{0, 1\}^{\Lambda}$ as

$$ext{bra}_{ji}(x)(k) := \left\{egin{array}{ll} x(i) \lor x(j) & ext{if } k = i, \ x(k) & ext{otherwise,} \end{array}
ight.$$

and a death map $\mathtt{dth}_i: \{0,1\}^{\Lambda} \to \{0,1\}^{\Lambda}$ as

$$\mathtt{dth}_i(x)(k) := \left\{egin{array}{ll} 0 & ext{if } k=i, \ x(k) & ext{otherwise.} \end{array}
ight.$$

Then the generator of the contact process has the random mapping representation

$$egin{aligned} Gf(x) &= \sum_{i,j\in\Lambda}\lambda(j,i)ig\{fig(extsf{bra}_{ji}(x)ig) - fig(x)ig\} \ &+ \sum_{i\in\Lambda}ig\{fig(extsf{dth}_i(x)ig) - fig(x)ig\} \quad & (x\in\{0,1\}^\Lambda). \end{aligned}$$

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We visualise the Poisson point set ω by drawing space Λ horizontally and time \mathbb{R} vertically.

For each $(bra_{ji}, t) \in \omega$ we draw an arrow from (j, t) to (i, t). For each $(dth_{ji}, t) \in \omega$ we draw a blocking symbol \blacksquare at (i, t).

It is easy to check that if we evolve the process under the stochastic flow $(X_{s,u})_{s \le u}$, then in the state x, the site i flips from 0 to 1 at rate $\sum_{i \in \Lambda} x(j)\lambda(j, i)$, and from 1 to 0 at rate 1.

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The graphical representation



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Let \oplus denote addition modulo 2.

For each $i, j \in \Lambda$, we define an annihilating branching map $abr_{ji} : \{0, 1\}^{\Lambda} \to \{0, 1\}^{\Lambda}$ as

$$\operatorname{abr}_{ji}(x)(k) := \begin{cases} x(i) \oplus x(j) & \text{if } k = i, \\ x(k) & \text{otherwise.} \end{cases}$$

The cancellative contact process has the generator

$$egin{aligned} & {\it Gf}(x) = \sum_{i,j\in\Lambda} \lambda(j,i)ig\{fig(extsf{abr}_{ji}(x)ig) - fig(x)ig\} \ &+ \sum_{i\in\Lambda}ig\{fig(extsf{dth}_i(x)ig) - fig(x)ig\} \ & (x\in\{0,1\}^\Lambda). \end{aligned}$$

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For $x, y \in \mathbf{S}$ that differ only in one site $i \in \Lambda$, let

$$G(x,y) := \begin{cases} 1 & \text{if } x(i) \neq x(j) \text{ for some } j \sim i, \\ 0 & \text{otherwise.} \end{cases}$$

and let G(x, y) := 0 if x and y differ in more than one site.

The Markov process with generator G is called the *threshold voter model*.

First random mapping representation

For each $i \in \Lambda$, we define maps min_i and max_i by

$$\min_i(x)(k) := \begin{cases} \bigwedge_{j \sim i} x(j) & \text{ if } k = i, \\ x(k) & \text{ otherwise,} \end{cases}$$

and

$$\max_i(x)(k) := \left\{ egin{array}{ll} \bigvee_{j\sim i} x(j) & ext{ if } k=i, \ x(k) & ext{ otherwise.} \end{array}
ight.$$

Then the generator of the threshold voter model has the random mapping representation

$$egin{aligned} Gf(x) &= \sum_{i \in \Lambda} \left\{ f\left(\min_i(x)
ight) - f\left(x
ight)
ight\} \ &+ \sum_{i \in \Lambda} \left\{ f\left(\max_i(x)
ight) - f\left(x
ight)
ight\} \qquad (x \in \{0,1\}^\Lambda). \end{aligned}$$

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Let $\mathcal{N}_i := \{i\} \cup \{j : j \sim i\}.$

For each $i \in \Lambda$ and $\Delta \subset \mathcal{N}_i$, we define a map $\texttt{flip}_{i,\Delta}$ by

$$\texttt{flip}_{i,\Delta}(x)(k) := \left\{ egin{array}{ll} \bigoplus_{j\in\Delta} x(j) & ext{ if } k=i, \ x(k) & ext{ otherwise.} \end{array}
ight.$$

Then the generator of the threshold voter model has the random mapping representation

$$Gf(x) = \sum_{i \in \Lambda} 2^{-|\mathcal{N}_i|} \sum_{\substack{\Delta \subset \mathcal{N}_i \\ |\Delta| \text{ is odd}}} \{f(\texttt{flip}_{i,\Delta}(x)) - f(x)\}.$$

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Note there are $2^{|\mathcal{N}_i|-1}$ odd subsets of \mathcal{N}_i .

We claim the threshold voter mode has the following description:

- Each site *i* is activated with Poisson rate 2.
- If i is activated, we uniformly chose an odd subset Δ ⊂ N_i and apply flip_{i.Δ}.

If x(j) = 0 for all $j \in \mathcal{N}_i$ then $\bigoplus_{j \in \Delta} x(j) = 0$ for all odd $\Delta \subset \mathcal{N}_i$ so flip_{*i*, Δ} does nothing.

If x(j) = 1 for all $j \in \mathcal{N}_i$ then $\bigoplus_{j \in \Delta} x(j) = 1$ for all odd $\Delta \subset \mathcal{N}_i$ so flip_{*i*, Δ} does nothing.

In all other cases, $\Delta \cap \{j \in \mathcal{N}_j : x(j) = 1\}$ is uniformly chosen from all subsets of $\{j \in \mathcal{N}_j : x(j) = 1\}$ so $\bigoplus_{j \in \Delta} x(j)$ is uniformly distributed on $\{0, 1\}$ and there is a probability 1/2 that $\texttt{flip}_{i,\Delta}$ changes the local state at *i*.

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We wish to define the (cancellative) contact process, the threshold voter model, and many more interacting particle systems also when Λ is countably infinite.

As before, we let $\boldsymbol{S}=\{0,1\}^{\Lambda},$ and we set

$$\mathbf{S}_{ ext{fin}} := ig\{ x \in \mathbf{S} : |x| < \infty ig\} \quad ext{with} \quad |x| := \sum_{i \in \Lambda} x(i).$$

Note that S_{fin} (contrary to S) is countable.

We first extend the Poisson construction of Markov processes to countable state space.

Let **S** be a countably infinite set and let $\overline{\mathbf{S}} := \mathbf{S} \cup \{\infty\}$ be its one-point compactification, i.e., $\mathbf{S} \ni x_n \to \infty$ iff for all finite $\mathbf{S}' \subset \mathbf{S}$ there is an $N < \infty$ such that $x_n \notin \mathbf{S}'$ for all n > N.

Let \mathcal{G} be a countable set whose elements are functions $m : \mathbf{S} \to \mathbf{S}$. Let $(r_m)_{m \in \mathcal{G}}$ be nonnegative rates.

For $x \in \mathbf{S}$, we set

$$\mathcal{G}_{x}:=\big\{m\in\mathcal{G}:m(x)\neq x\big\}$$

and we assume that

$$\sum_{m\in\mathcal{G}_x}r_m<\infty\qquad(x\in\mathbf{S}).$$

As before let ρ be the measure on $\mathcal{G}\times\mathbb{R}$ defined by

$$\rho(\{m\}\times[s,t]):=r_m(t-s) \qquad (m\in\mathcal{G},\ s\leq t).$$

Let ω be a Poisson point set on $\mathcal{G} \times \mathbb{R}$ with intensity ρ .

Recall that a function f defined on a real interval is *cadlag* if it is right-continuous and the left-limit $f_{t-} := \lim_{s \uparrow t} f_s$ exists for all t.

Lemma For all $s \in \mathbb{R}$ and $x \in S$, there exists a unique cadlag function $[s, \infty) \ni t \mapsto X_t \in \overline{S}$ and time $0 < \tau \le \infty$ such that

- 1. $X_s = x$,
- 2. $X_t = m(X_{t-})$ if $(m, t) \in \omega$ for some necessarily unique $m \in \mathcal{G}$ and $X_t = X_{t-}$ otherwise $(t \in [0, \tau))$.
- 3. If $\tau < \infty$, then $\lim_{t\uparrow\tau} X_t = \infty$ and $X_t = \infty$ for all $t \ge \tau$.

If $\tau < \infty$, then we say that the Markov process *explodes*. To prove that the process is nonexplosive, it suffices to find a Lyapunov function.

Lemma Assume that there exists a function $L : \mathbf{S} \to [0, \infty)$ such that $L(x) \to \infty$ as $x \to \infty$, and a constant $K < \infty$ such that

$$GL(x) \leq KL(x)$$
 $(x \in \mathbf{S}).$

Then $\tau = \infty$ a.s. and the process started in $X_s = x$ satisfies

$$\mathbb{E}^{\mathsf{X}}[\mathsf{L}(\mathsf{X}_t)] \leq e^{\mathsf{K}(t-s)}\mathsf{L}(\mathsf{X}) \qquad (s \leq t, \ \mathsf{X} \in \mathbf{S}).$$

We define random maps $(X_{s,u})_{s \leq u}$ by

$$\mathbb{X}_{s,u}(x):=X_u$$
 where $(X_t)_{t\geq s}$ satisfies 1–3.

Recall the generator of the contact process

$$egin{aligned} & {\it Gf}(x) = \sum_{i,j\in\Lambda} \lambda(j,i) ig\{ fig(\mathtt{bra}_{ji}(x) ig) - fig(x ig) ig\} \ &+ \sum_{i\in\Lambda} ig\{ fig(\mathtt{dth}_i(x) ig) - fig(x ig) ig\} \qquad (x\in\{0,1\}^{\Lambda}). \end{aligned}$$

As before, let

$$\mathbf{S}_{ ext{fin}} := ig\{ x \in \mathbf{S} : |x| < \infty ig\} \quad ext{with} \quad |x| := \sum_{i \in \Lambda} x(i).$$

We use the Lypapunov function L(x) := |x|. Provided that

$$\mathcal{K} := \sup_{j \in \Lambda} \sum_{i \in \Lambda} \lambda(j, i) < \infty,$$

we have $GL(x) \leq KL(x)$ ($x \in S_{fin}$) and the contact process with state space S_{fin} is well-defined.

The methods so far allow us to construct the (cancellative) contact process, the threshold voter model, and many more interacting particle systems for initial states $x \in \{0, 1\}^{\Lambda}$ such that $|x| < \infty$.

We wish to allow initial states x with $|x| = \infty$.

We replace $\{0,1\}$ by a general finite set *S*, the *local state space*. We let Λ be a countable set, called the *lattice*. We let $\mathbf{S} := S^{\Lambda}$ denote the space of all functions $x : \Lambda \to S$. We equip S^{Λ} with the product topology, under which it is compact.

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As before, for $x \in S^{\Lambda}$ and $\Delta \subset \Lambda$, we let

$$x_{\Delta} = (x(i))_{i \in \Delta}$$

denote the restriction of x to Δ .

Lemma Let T be a finite set. Then a function $f : S^{\Lambda} \to T$ is continuous if and only if it depends on finitely many coordinates, i.e., there exists a finite set $\Delta \subset \Lambda$ and a function $f' : S^{\Delta} \to T$ such that $f(x) = f'(x_{\Delta})$ $(x \in S^{\Lambda})$.

For any function $f: S^{\Lambda} \to T$, we call

 $\mathcal{R}(f) := \big\{ i \in \Lambda : \exists x, y \in S^{\Lambda} \text{ s.t. } f(x) \neq f(y) \text{ and } x_{\Lambda \setminus \{i\}} = y_{\Lambda \setminus \{i\}} \big\}.$

the set of *f*-relevant sites.

If f is continuous, then $\mathcal{R}(f)$ is the smallest possible finite set $\Delta \subset \Lambda$ such that there exists a function $f' : S^{\Delta} \to T$ with $f(x) = f'(x_{\Delta}) \ (x \in S^{\Lambda})$.

If f is not continuous, then strange things can happen:

Example Set $S = T := \{0, 1\}$ and f(x) := 1 iff $\{i \in \Lambda : x(i) = 1\}$ is finite. Then $\mathcal{R}(f) = \emptyset$, but f is not constant.

Example Set $S = T := \{0, 1\}$ and f(x) := 1 iff $\{i \in \Lambda : x(i) = 1\}$ is finite and even. Then $\mathcal{R}(f) = \Lambda$.

Local maps

For any map $m: S^{\Lambda} \to S^{\Lambda}$ and $i \in \Lambda$, we define $m[i]: S^{\Lambda} \to S$ by $m[i](x) := m(x)(i) \qquad (x \in S^{\Lambda}).$

Then *m* is continuous iff m[i] is continuous for all $i \in \Lambda$.

By definition, a map $m: S^{\Lambda} \rightarrow S^{\Lambda}$ is *local* iff

1. *m* is continuous,

2.
$$\mathcal{D}(m) := \{i \in \Lambda : \exists x \in S^{\Lambda} \text{ s.t. } m(x)(i) \neq x(i)\}$$
 is finite.

We will be interested in interacting particle systems with generator of the form

$$Gf(x) = \sum_{m \in \mathcal{G}} r_m \{f(m(x)) - f(x)\},\$$

where \mathcal{G} is a countable set whose elements are local functions $m: S^{\Lambda} \to S^{\Lambda}$ and $(r_m)_{m \in \mathcal{G}}$ are nonnegative rates.

Poisson construction of particle systems

Theorem Assume that

$$\sup_{i\in\Lambda} \sum_{\substack{m\in\mathcal{G}\\\mathcal{D}(m)\ni i}} r_m(|\mathcal{R}(m([i])|+1) < \infty.$$

Then almost surely, for each $s \in \mathbb{R}$ and $x \in S^{\Lambda}$, there exists a unique cadlag function $(X_t)_{t \ge s}$ such that

1.
$$X_s = x_s$$

2. $X_t = m(X_{t-})$ if $(m, t) \in \omega$ for some necessarily unique $m \in \mathcal{G}$ and $X_t = X_{t-}$ otherwise.

We define random maps $(\mathbb{X}_{s,u})_{s\leq u}$ by

$$\mathbb{X}_{s,u}(x) := X_u$$
 where $(X_t)_{t \ge s}$ satisfies 1–2.

If X_0 is independent of ω and $s \in \mathbb{R}$, then

$$X_t := \mathbb{X}_{s,s+t}(X_0) \qquad (t \ge 0)$$

is a Markov process $(X_t)_{t\geq 0}$ with generator G_{\cdot}

Idea of the proof Fix a finite "target" set T.

Then the set $\mathcal{C}(S^{\Lambda}, T)$ of continuous functions $f : S^{\Lambda} \to T$ is countable.

For fixed $f \in C(S^{\Lambda}, T)$ and $u \in \mathbb{R}$, we want the *backtracking* process

$$(F_t)_{t\geq 0}:=\left(f\circ\mathbb{X}_{u-t,t}\right)_{t\geq 0}$$

to be a well-defined Markov process with state space $\mathcal{C}(S^{\Lambda}, \mathcal{T})$ and generator

$$H\mathcal{F}(f) := \sum_{m \in \mathcal{G}} r_m \{ \mathcal{F}(f \circ m) - \mathcal{F}(f) \}.$$

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The backtracking process



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The backtracking process

The condition

$$\sup_{i \in \Lambda} \sum_{\substack{m \in \mathcal{G} \\ \mathcal{D}(m) \ni i}} r_m < \infty$$

guarantees that

$$\sum_{\substack{m \in \mathcal{G} \\ f \circ m \neq f}} r_m < \infty \qquad (f \in \mathcal{C}(S^{\Lambda}, T)),$$

and the Lyapunov function

$$L(f) := |\mathcal{R}(f)| \qquad (f \in \mathcal{C}(S^{\Lambda}, T)),$$

satisfies $HL(f) \leq KL(f)$ with

$$\mathcal{K} := \sup_{i \in \Lambda} \sum_{\substack{m \in \mathcal{G} \\ \mathcal{D}(m) \ni i}} r_m |\mathcal{R}(m([i])|.$$

Examples

The contact process is well-defined for arbitrary initial states $x \in \{0,1\}^{\Lambda}$ provided that

$$\sup_{i\in\Lambda}\sum_{j\in\Lambda}\lambda(j,i)<\infty.$$

Note that earlier, we proved that $|X_0| < \infty$ implies that $|X_t| < \infty$ for all $t \ge 0$ provided that

$$\sup_{j\in\Lambda}\sum_{i\in\Lambda}\lambda(j,i)<\infty.$$

Our theorem implies that the threshold voter model is well-defined provided the graph Λ is of uniformly bounded degree. (This condition can be relaxed by a more clever choice of the Lyapunov function.)

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The backward stochastic flow

We set

$$\mathbb{F}_{u,s}(f) := f \circ \mathbb{X}_{s,u} \qquad (u \ge s, \ f \in \mathcal{C}(S^{\Lambda}, T)).$$

Then $(\mathbb{F}_{u,s})_{u\geq s}$ is a backward stochastic flow:

$$\mathbb{F}_{s,s} = 1$$
 and $\mathbb{F}_{t,s} \circ \mathbb{F}_{u,t} = \mathbb{X}_{s,u}$ $(u \ge t \ge s).$

If F_0 is a random variable with values in $\mathcal{C}(S^{\Lambda}, T)$, independent of ω , and $u \in \mathbb{R}$, then

$$F_t := \mathbb{F}_{u,u-t}(F_0) \qquad (t \ge 0)$$

defines a Markov process $(F_t)_{t\geq 0}$ with generator H. It is a consequence of our construction that this *backtracking* process has caglad sample paths, i.e., $t \mapsto F_t$ left-continuous and the right limit $F_{t+} := \lim_{s\downarrow t} F_s$ exists for all $t \geq 0$.

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